

# The Quantum Consensus Principle

A Thermodynamic Information Principle  
for Quantum Measurement

Emergent Collapse from Large-Deviation Consensus Dynamics  
in Open Quantum Systems

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March 2026

## Abstract

Standard formulations of quantum measurement do not by themselves provide a universally accepted dynamical account of single-outcome selection. Within standard open-system quantum mechanics, the Quantum Consensus Principle (QCP) proposes a unified framework connecting microscopic detector dynamics, operational outcome statistics, and apparatus dependence.

Starting from a microscopic Hamiltonian description of system, apparatus, and environment dynamics, we derive a deformed positive operator-valued measure (POVM)

$$E_i = \sum_{j=1}^d S_{ij} \Pi_j, \quad S_{ij} \geq 0, \quad \sum_{i=1}^d S_{ij} = 1 \quad \forall j, \quad (1)$$

whose weights depend on two canonical functionals of the apparatus response: the redundancy rate  $\tilde{R}_i$  and the noise susceptibility  $\chi_i$ . These quantities, defined in the Bogoliubov–Kubo–Mori (BKM) information geometry of the apparatus, are tied to microscopic Hamiltonian parameters via Green–Kubo transport coefficients  $a(T, \eta, J)$  and  $b(T, \eta, J)$ .

Within the admissible class specified in the companion Supplement [companion Supplement]—causal CPTP dynamics on process-tensor path space, data-processing inequality (DPI) monotonicity, exact concatenation additivity, convexity/lower semi-continuity, and the stated KMS/regularity assumptions—the effective selection functional is unique up to affine gauge and, after calibration of the canonical sufficient statistics, takes the linear form  $\Phi_i = a \tilde{R}_i + b_i \chi_i$ . Competing nonlinear selectors are excluded within that explicit admissible class.

We establish that the conditioned system state forms a Hellinger contractive supermartingale, converging almost surely (i.e. with probability one) to a unique pointer state  $\Pi_{i^*}$ . Outcome probabilities follow from a path-space large-deviation principle, reproducing Born’s rule in the apparatus-neutral limit and predicting measurable deviations for biased apparatuses. QCP yields a non-monotonic collapse timescale  $\tau_{\text{coll}}(\kappa)$  with a unique optimal measurement strength  $\kappa_{\text{opt}} = a/b$ . These results identify quantum measurement as a thermodynamic consensus phenomenon,

deriving collapse, outcome statistics, and apparatus dependence directly from Hamiltonian physics without modifying quantum mechanics.

**Scope.** The present main paper states the physical architecture of QCP and its front-end consequences in the Markovian pointer-preserving regime. The full admissibility, uniqueness, calibration, process-tensor extension, and counterexample-exclusion proofs are carried by the companion Supplement [companion Supplement] and notes [companion Born addendum; Necessity note]. The strongest claims are conditional on those standing assumptions and calibration conditions, rather than unrestricted statements about arbitrary detector models.

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# 1 Introduction

Quantum measurement presents an unresolved structural gap: the unitary Liouvillian dynamics of quantum systems does not produce single outcomes, yet experiments do. Projection postulates [1, 2, 3] formalize collapse without mechanism; Everettian branches [4] preserve unitarity at the cost of ontic multiplicity. Objective collapse theories [5, 6, 7] modify the Schrödinger equation, and Bohmian mechanics [8] introduces hidden configuration-space trajectories. None explain how real detectors amplify microscopic information into macroscopic consensus. Open quantum systems theory [9, 10, 11, 12] and decoherence/einselection approaches [13] provide precise dynamical tools, but no existing framework derives the emergence of a unique pointer state, the Born rule, and the apparatus dependence of measurement statistics from a single principle.

Here we introduce the *Quantum Consensus Principle* (QCP): a universal information-theoretic mechanism by which measurement outcomes arise from large-deviation consensus selection in macroscopic detectors. QCP produces a mathematically rigorous collapse, quantitative timescales, auditability from microscopic Hamiltonians, and experimentally accessible deviations from Born statistics.

Detailed derivations and mathematical proofs are provided in the companion Supplement [companion Supplement]. A separate companion note [companion Necessity note] provides the complementary necessity statement: under explicit bare recorded unitary hypotheses, deterministic state-only one-world outcome selection is excluded on the reachable recorded state space.

## 2 Microscopic Model and Conditional Dynamics

### 2.1 Total Hamiltonian

Consider a measured system  $S$ , a macroscopic apparatus  $A$ , and a thermal environment  $E$  governed by the total Hamiltonian

$$H = H_S + H_A + H_E + H_{\text{int}}. \quad (2)$$

**Definition 2.1** (Pointer projectors). The pointer projectors  $\{\Pi_i\}_{i=1}^d \subset \mathcal{B}(\mathcal{H}_S)$  form an orthogonal projection-valued measure (PVM) on the system Hilbert space  $\mathcal{H}_S$ :

$$\Pi_i \Pi_j = \delta_{ij} \Pi_i, \quad \Pi_i = \Pi_i^\dagger, \quad \sum_{i=1}^d \Pi_i = \mathbf{1}_S. \quad (3)$$

**Definition 2.2** (Positive operator-valued measure (POVM)). A POVM on  $\mathcal{H}_S$  is a set  $\{E_i\}_{i=1}^d$  of positive semidefinite operators satisfying  $E_i \geq 0$  and  $\sum_{i=1}^d E_i = \mathbf{1}_S$ . The probability of outcome  $i$  for a system in state  $\rho$  is  $P(i|\rho) = \text{Tr}(E_i \rho)$ .

The interaction term has the pointer-selective coupling form

$$H_{\text{int}} = \sum_{j=1}^d \Pi_j \otimes B_j, \quad (4)$$

where  $B_j \in \mathcal{B}(\mathcal{H}_E)$  are bath operators satisfying KMS detailed-balance relations. Each channel  $j$  couples the pointer sector  $\Pi_j$  to its own bath operator  $B_j$ .

## 2.2 Lindblad generator

Under the standard weak-coupling, rotating-wave, and coarse-graining approximations (collectively the Born–Markov–Secular approximation [9, 14, 17]), the conditional dynamics of the reduced system state  $\rho_t := \text{Tr}_E(\rho_{\text{tot},t})$  is governed by the stochastic master equation

$$d\rho_t = \mathcal{L}(\rho_t) dt + \sum_{i=1}^d \left( \frac{\Pi_i \rho_t \Pi_i}{\text{Tr}(\Pi_i \rho_t)} - \rho_t \right) (dN_i(t) - \lambda_i(\rho_t) dt), \quad (5)$$

with Lindblad generator

$$\mathcal{L}(\rho) = -i[H_{\text{eff}}, \rho] + \sum_{i=1}^d \left( L_i \rho L_i^\dagger - \frac{1}{2} \{L_i^\dagger L_i, \rho\} \right), \quad (6)$$

and jump operators

$$L_i = \sqrt{\kappa_i} \Pi_i, \quad \kappa_i = 2\pi \|A_i\|^2 S_E(\omega_i) > 0. \quad (7)$$

Here  $S_E(\omega)$  is the bath spectral density,  $A_i$  are the coupling operators entering the interaction Hamiltonian, and  $\{dN_i(t)\}$  are Poisson increments with intensities  $\lambda_i(\rho) = \kappa_i \text{Tr}(\Pi_i \rho)$ .

*Remark 2.3* (Coupling operators). The Golden-Rule rates (7) involve the coupling operators  $A_i$  that appear in the Supplement’s factored interaction form  $H_{\text{int}} = \sum_j \Pi_j \otimes A_j \otimes B$ , where  $B$  is a collective bath operator. Identifying  $B_j := A_j \otimes B$  in the appropriate contraction recovers the channel-specific form (4) used here, with  $\kappa_i = 2\pi \|A_i\|^2 S_E(\omega_i)$ .

**Assumption 2.4** (QND / Pointer invariance). The effective Hamiltonian  $H_{\text{eff}} = H_S + H_{\text{LS}}$  (where  $H_{\text{LS}}$  is the Lamb shift) commutes with every pointer projector:

$$[H_{\text{eff}}, \Pi_i] = 0 \quad \text{for all } i = 1, \dots, d. \quad (8)$$

This quantum non-demolition (QND) condition ensures that the pointer basis is preserved under the coherent part of the dynamics. The jump rates  $\kappa_i$  follow directly from Fermi’s Golden Rule and the bath spectral density  $S_E(\omega)$ ; upward/downward rates for non-QND couplings obey KMS relations [9]. QCP uses no phenomenological parameters: all apparatus asymmetries enter through  $\kappa_i$  and through correlation functions defining the canonical scores below.

**Standing assumptions.** The following assumptions, inherited from the companion Supplement, are in force throughout this paper:

**(A1) Valid Lindblad dynamics.**

The reduced system state  $\rho_t \in \mathcal{S}(\mathcal{H}_S)$  evolves via (6) with jump operators (7).

**(A2) Pointer invariance / QND.**

$[H_{\text{eff}}, \Pi_i] = 0$  for all  $i$  (Assumption 2.4); equivalently  $[H_S, \Pi_i] = 0$ , since  $[H_{\text{LS}}, \Pi_i] = 0$  under the Secular approximation.

**(A3) Dephasing dominance.**

Off-diagonal elements of  $\rho$  in the pointer basis decay exponentially under the dynamics, guaranteeing classicalization of trajectories.

**(A4) Identifiability.**

The Kullback–Leibler divergence rate between trajectory statistics generated by any two distinct pointer states  $\Pi_i \neq \Pi_j$  is strictly positive.

In addition, the bath assumptions (BKM/KMS) and the regularity assumption (A\*) of the companion Supplement remain in force.

### 3 Canonical Scores: Redundancy and Susceptibility

Macroscopic detectors amplify microscopic alternatives via large networks of degrees of freedom. For each output channel  $i$ , QCP defines two canonical scores in terms of current operators on the apparatus Hilbert space. The *information current*  $\mathcal{I}_i$  measures the rate at which the apparatus subsystem coupled to channel  $i$  produces distinguishable records; concretely, it is the operator whose BKM norm gives the mutual-information production rate between pointer sector  $i$  and the environment fragment. The *noise current*  $\mathcal{B}_i$  measures the rate at which thermal fluctuations and entanglement-induced noise degrade the recorded information in channel  $i$ .

**Definition 3.1** (Redundancy rate). The redundancy rate  $\tilde{R}_i$  is the asymptotic rate at which stable, distinguishable information about outcome  $i$  is produced in the apparatus:

$$\tilde{R}_i = \langle \mathcal{I}_i, \mathcal{I}_i \rangle_{\text{BKM}}, \quad (9)$$

where  $\mathcal{I}_i$  is the information-current operator and  $\langle \cdot, \cdot \rangle_{\text{BKM}}$  denotes the Bogoliubov–Kubo–Mori (BKM) inner product [15] on the apparatus state space.

**Definition 3.2** (Noise susceptibility). The noise susceptibility  $\chi_i$  is the sensitivity of the apparatus record to thermal and entanglement-induced noise:

$$\chi_i = \langle \mathcal{B}_i, \mathcal{B}_i \rangle_{\text{BKM}}, \quad (10)$$

where  $\mathcal{B}_i$  is the noise-current operator.

**Definition 3.3** (Green–Kubo coefficients). The transport coefficients  $a(T, \eta, J)$  and  $b(T, \eta, J)$  entering the QCP potential are given by linear-response integrals [22]:

$$a = \int_0^\infty \langle \mathcal{I}_i(t) \mathcal{I}_i(0) \rangle_{\rho_E} dt, \quad b = \int_0^\infty \langle \mathcal{B}_i(t) \mathcal{B}_i(0) \rangle_{\rho_E} dt, \quad (11)$$

where  $\langle \cdot \rangle_{\rho_E}$  denotes the expectation with respect to the KMS equilibrium state of the bath at inverse temperature  $\beta$ . These link  $\Phi_i$  directly to the microscopic Hamiltonian. The scores  $(\tilde{R}_i, \chi_i)$  are static information-geometric quantities, while  $a, b$  quantify dynamical transport.

*Remark 3.4* (Notation convention). We use the standard Lindblad normalization  $L_i = \sqrt{\kappa_i} \Pi_i$ , where  $\kappa_i$  are Golden-Rule jump rates. For channel-resolved outcome competition we write  $\Phi_i = a\tilde{R}_i + b\chi_i$ . In symmetric or one-parameter calibration scans we use the reduced notation  $\Phi_{\text{scan}}(\kappa) := b\chi(\kappa) - a\tilde{R}(\kappa)$  and define the scalar scan functional as a coupling-tuning functional. This is *not* a redefinition of the channel selector  $\Phi_i$ ; the sign inversion reflects the cost-minus-gain interpretation appropriate for locating the minimum of the scan [companion Supplement, Notation convention, p. S-3].

### 4 The Quantum Consensus Potential

**Theorem 4.1** (Admissible linear selector; main-paper form). *Within the explicit admissible class defined in the companion Supplement [companion Supplement]—causal CPTP/process-tensor dynamics, DPI monotonicity, exact concatenation additivity, convexity/lower semicontinuity, and the stated support/KMS regularity assumptions—the*

*QCP selection functional is unique up to affine gauge. After identification of the two canonical sufficient statistics  $\tilde{R}_i$  and  $\chi_i$ , this yields the calibrated linear form*

$$\Phi_i = a \tilde{R}_i + b_i \chi_i. \quad (12)$$

*The stronger path-space uniqueness and no-competing-divergence statements are proved in the Supplement [companion Supplement, Theorem 10.1, Corollary 10.2]. Competing nonlinear selectors are excluded within the above admissible class; outside that class, no such claim is made.*

*Remark 4.2 (Non-monotonic collapse time).* When scanning over measurement strength  $\kappa$ , the effective scan potential  $\Phi_{\text{scan}}(\kappa) = b \chi(\kappa) - a \tilde{R}(\kappa)$  has a U-shaped profile with a unique minimum at

$$\kappa_{\text{opt}} = \frac{a}{b}. \quad (13)$$

Within the calibrated scan family considered here, this structure underlies a non-monotonic collapse time  $\tau_{\text{coll}}(\kappa) \sim 1/\gamma_{\text{min}}(\kappa)$ . This prediction is absent from all standard models (Copenhagen, Many-Worlds, Bohm, GRW). See [companion Supplement, Section 9.2] for the detailed derivation.

## 5 Large-Deviation Derivation of Outcome Probabilities

Let  $\rho_t$  denote the conditional state trajectory. Using a Doob  $h$ -transform of the path measure [18] (see [companion Supplement, Section 4] for the full construction), we establish the trajectory-level large-deviation principle [16]

$$\mathbb{P}(\rho_T \rightarrow \Pi_i) \asymp \exp[-T \Phi_i], \quad (14)$$

where  $\asymp$  denotes logarithmic equivalence in the sense of large-deviation theory [16]:

$$\lim_{T \rightarrow \infty} \frac{1}{T} \log \mathbb{P}(\rho_T \rightarrow \Pi_i) = -\Phi_i.$$

Normalization defines a column-stochastic response matrix  $S$  and the QCP POVM:

$$E_i := \sum_{j=1}^d S_{ij} \Pi_j, \quad S_{ij} \geq 0, \quad \sum_{i=1}^d S_{ij} = 1 \quad \forall j, \quad P(i|\rho) = \text{Tr}(E_i \rho). \quad (15)$$

### 5.1 Operational probability law and neutral limit

In QCP, outcome probabilities are defined operationally as asymptotic frequencies of stochastic trajectories (see [companion Born addendum, Definition 3.1]). They are *not* postulated at the level of measurement outcomes. For a general calibrated instrument, the exact output law is

$$P(I^* = i) = \text{Tr}(E_i \rho_0), \quad E_i = \sum_j S_{ij} \Pi_j, \quad (16)$$

with  $S$  column-stochastic.

**Definition 5.1** (Neutral apparatus). The apparatus is *neutral* if  $S = I$  (the identity matrix), equivalently  $E_i = \Pi_i$  for all  $i$ . By Corollary 2.6 of the Supplement [companion Supplement], this is the limit in which  $\Phi_i = \text{const}$  across channels.

In the neutral case, the posterior process  $M_i(t) := \text{Tr}(\Pi_i \rho_t)$  is a bounded martingale ([companion Born addendum, Theorem 4.1]), and together with almost-sure collapse to pointer sectors this yields

$$P(I^* = i) = \text{Tr}(\Pi_i \rho_0). \quad (17)$$

Thus the Born rule is the exact trajectory-frequency law of the neutral instrument, not an independent probability postulate [companion Born addendum]. Away from neutrality, first-order deviations are stated only for smooth response-matrix families  $S(\varepsilon)$ ; see [companion Born addendum, Theorem 6.3].

*Remark 5.2* (Born is not presupposed). Corollary 6.5 of the Born addendum [companion Born addendum] establishes:  $P(I^* = i) = \text{Tr}(\Pi_i \rho_0)$  for all states and all  $i$  if and only if  $S = I$ . Since QCP predicts apparatus-dependent deviations whenever  $S \neq I$ , it follows by *modus tollens* that Born is not an axiom of QCP but a derived fixed-point property of the neutral instrument.

## 6 Emergent Collapse Dynamics

The stochastic process  $\{\rho_t\}$  is a supermartingale under the natural filtration generated by measurement events. We construct a Lyapunov functional from the squared Hellinger distance to the nearest pointer-state vertex:

**Definition 6.1** (Hellinger-Lyapunov functional). Let  $p_k(\rho) := \text{Tr}(\Pi_k \rho)$  be the pointer probabilities and  $e_k$  the  $k$ -th standard basis vector. Define

$$\mathcal{V}(\rho) := \min_{k \in \{1, \dots, d\}} D_H^2(p(\rho), e_k) = 2 \left( 1 - \max_k \sqrt{p_k(\rho)} \right), \quad (18)$$

where  $D_H^2(p, q) := \sum_i (\sqrt{p_i} - \sqrt{q_i})^2$  is the squared Hellinger distance [23]. The functional  $\mathcal{V}$  is non-negative and equals zero if and only if  $\rho$  is a pointer state ( $p = e_k$  for some  $k$ ).

**Theorem 6.2** (Consensus collapse). *Under the standing assumptions (A1)–(A4) [companion Supplement, Section 3], the conditioned state process admits a Hellinger-type Lyapunov functional and converges almost surely (i.e. with probability one, in the measure-theoretic sense of Doob’s supermartingale convergence theorem [25]) to a pointer projector:*

$$\rho_t \longrightarrow \Pi_{i^*} \quad \text{almost surely}, \quad (19)$$

where  $i^*$  is a random index determined by the trajectory. The exponential contraction bound is

$$\mathbb{E}[\mathcal{V}(\rho_t)] \leq e^{-\kappa_{\min} t} \mathcal{V}(\rho_0), \quad \kappa_{\min} := \min_i \kappa_i > 0. \quad (20)$$

The contraction rate  $\bar{\kappa}(p) := \sum_i \kappa_i p_i(\rho) \geq \kappa_{\min}$  is a monotone decreasing function of the potential: smaller  $\Phi_i$  implies larger spectral gap and faster collapse.

*Proof sketch* (full proof: [companion Supplement, Theorem 3.1, Lemma A.3]). The QND condition (8) ensures the Hamiltonian part of the generator preserves pointer probabilities. Each quantum jump into channel  $i$  sends the post-jump state to  $\sigma_i = \Pi_i \rho \Pi_i / \text{Tr}(\Pi_i \rho)$ , for which  $\mathcal{V}(\sigma_i) = 0$  exactly. Therefore the dissipative generator satisfies  $\mathcal{G}\mathcal{V}(\rho) = -\bar{\kappa}(p) \mathcal{V}(\rho) \leq -\kappa_{\min} \mathcal{V}(\rho)$ . Since  $\mathcal{V} \geq 0$ , Doob’s supermartingale convergence theorem gives  $\mathcal{V}(\rho_t) \rightarrow 0$  a.s., hence  $\rho_t \rightarrow \Pi_{i^*}$ .  $\square$

*Remark 6.3* (Non-monotonic collapse time). Because  $\Phi_{\text{scan}}(\kappa)$  is U-shaped,  $\gamma(\kappa)$  is  $\cap$ -shaped, and  $\tau_{\text{coll}}(\kappa) \sim 1/\gamma_{\text{min}}(\kappa)$  has a unique minimum at  $\kappa_{\text{opt}} = a/b$ . For weak coupling ( $\kappa \ll \kappa_{\text{opt}}$ ), the process is information-limited (insufficient redundancy amplification). For strong coupling ( $\kappa \gg \kappa_{\text{opt}}$ ), it becomes noise-limited (excessive thermal backaction). The optimal point  $\kappa_{\text{opt}}$  identifies the thermodynamically optimal consensus rate [companion Supplement, Section 9.2].

## 7 Non-Markovian Robustness

The Markovian pointer-preserving regime serves as the reference front-end model. The companion Supplement formulates the corresponding path-space uniqueness, POVM validity, and no-signalling statements on process-tensor path space [19, 20] under explicit causality, DPI, additivity, support, and KMS/regularity assumptions [companion Supplement, Section 2.12]; cf. [21] for the process-tensor framework.

Accordingly, robustness beyond Markov/QND is claimed only in that conditional sense. The formal derivation of the process-tensor formulation and the proof of invariance of the RSK-linear potential under non-Markovian dynamics are given in [companion Supplement, Section 2.12].

## 8 Predictions and Falsifiability

QCP makes several experimentally accessible predictions.

### 8.1 Non-monotonic collapse rate

In continuous-measurement platforms (superconducting qubits [29], NV centres, trapped ions), varying the measurement strength  $\kappa$  must yield a U-shaped collapse time  $\tau_{\text{coll}}(\kappa)$  with a device-specific optimum at  $\kappa_{\text{opt}} = a/b$  (13).

### 8.2 Born deviations for biased apparatus

**Definition 8.1** (Apparatus bias parameter). Let  $\beta \mapsto S(\beta)$  be a  $C^1$  family of column-stochastic response matrices with  $S(0) = I$ . The scalar parameter  $\beta \geq 0$  quantifies the deviation of the apparatus from neutrality; its value is determined by the microscopic apparatus data  $(T, \eta, J)$  through the calibrated map  $(T, \eta, J) \mapsto S$  of the companion Supplement. The neutral limit corresponds to  $\beta = 0$ , where Born statistics are recovered exactly.

For asymmetrically structured detectors with bias parameter  $\beta > 0$ ,

$$D_{\text{tr}}(P_{\text{QCP}}, P_{\text{Born}}) = O(\beta), \quad (21)$$

where  $D_{\text{tr}}$  denotes the trace distance between the QCP outcome distribution and the Born distribution. Modern POVM tomography [27, 28] can resolve such deviations.

### 8.3 Microscopic auditability

All parameters of QCP are operationally measurable:

- The microscopic coupling strengths  $\kappa_i$  can be determined from spectroscopy of the environmental response.
- The transport coefficients  $a$  and  $b$  are obtained from Green–Kubo integrals (11).
- The redundancy rates  $\tilde{R}_i$  and noise susceptibilities  $\chi_i$  can be extracted through partial monitoring of the environment.
- The effective measurement operators  $E_i$  are reconstructable via multi-strength quantum tomography [26, 27].

Together, these render QCP a fully falsifiable physical theory.

## 9 Comparison with Existing Frameworks

Framework	Outcome selection	Born rule	Distinctive predictions	Assumptions
Copenhagen	Postulated collapse	Axiom	None	Classical observer cut
Many-Worlds	None (all branches persist)	Derived (decision-theoretic)	None beyond standard QM	Ontology of branches
Bohmian mechanics	Deterministic pilot-wave	Reproduced	Nonlocal hidden variables	Additional particle ontology
GRW / CSL	Spontaneous localization	Modified	Heating, localization events	New fundamental constants
Quantum Darwinism [24]	Redundant environment encoding	Assumed	Spectrum-broadcast structure	Standard decoherence
<b>QCP</b>	<b>Thermodynamic attractor selection</b>	<b>Derived (martingale collapse)</b>	<b>Apparatus-dep. POVM deformation</b>	<b>Standard open QM dynamics</b>

Table 1: Comparison of quantum measurement frameworks. QCP is the only framework that (i) derives outcome selection from standard open-system dynamics, (ii) derives Born’s rule as a neutral fixed point, and (iii) predicts apparatus-dependent deviations.

## 10 Discussion

QCP reconceives measurement as an information-driven nonequilibrium phase-selection process. Collapse is not an exception inserted into the formalism; it is the inevitable attractor of redundancy-amplifying dynamics. The Born rule becomes a statement of apparatus neutrality, not a primitive axiom. The theory offers:

- no new ontology,
- no hidden variables,
- no nonlinear Schrödinger corrections,
- no branching universes.

Instead, outcome selection results from thermodynamic consensus, governed by universal constraints on CPTP maps, DPI, and information geometry. The formalism unifies quantum measurement with statistical physics: macroscopic measurement devices act as large-deviation engines, computing the most stable macroscopic alternative.

## 11 Conclusion

We have presented the Quantum Consensus Principle (QCP), a first-principles framework that derives quantum measurement as an emergent thermodynamic phenomenon. Starting from microscopic Hamiltonian dynamics and extending through information-geometric and path-space large-deviation formalisms, QCP provides a unified and quantitatively predictive description of measurement.

In the Markovian pointer-preserving regime emphasized here, and under the standing assumptions carried by the companion materials [companion Supplement; Born addendum], QCP yields:

- (i) an almost-sure collapse architecture (Theorem 6.2);
- (ii) an apparatus-dependent POVM description (15);
- (iii) a non-monotonic calibrated collapse-time prediction (Remark 6.3).

In the neutral instrument limit  $S = I$ , the Born law is recovered as the exact operational trajectory-frequency law (17) [companion Born addendum]; away from neutrality, calibrated response matrices generate controlled POVM-level deviations that are, in principle, experimentally testable.

By grounding outcome selection in the universal thermodynamics of information production, QCP transforms the measurement problem from an interpretational postulate into a derived physical process.

A separate companion note [companion Necessity note] supplies a narrower necessity statement: under bare recorded unitary dynamics, explicit record hypotheses, support faithfulness, and reachable relabelling covariance, no deterministic state-only single-outcome selector exists on the reachable recorded state space. This closes one direct state-only route within the stated formal setting, while the positive uniqueness of the admissible path-space selector remains the independent content of the companion Supplement [companion Supplement].

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